

# *Delay Differential Equations*

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# Mackey-Glass Equation

## Mackey-Glass Equation

$$\dot{u}(t) = -\gamma u(t) + \beta \frac{u(t-\tau)}{1+u(t-\tau)^n}, \quad u(t) \in \mathbb{R}$$

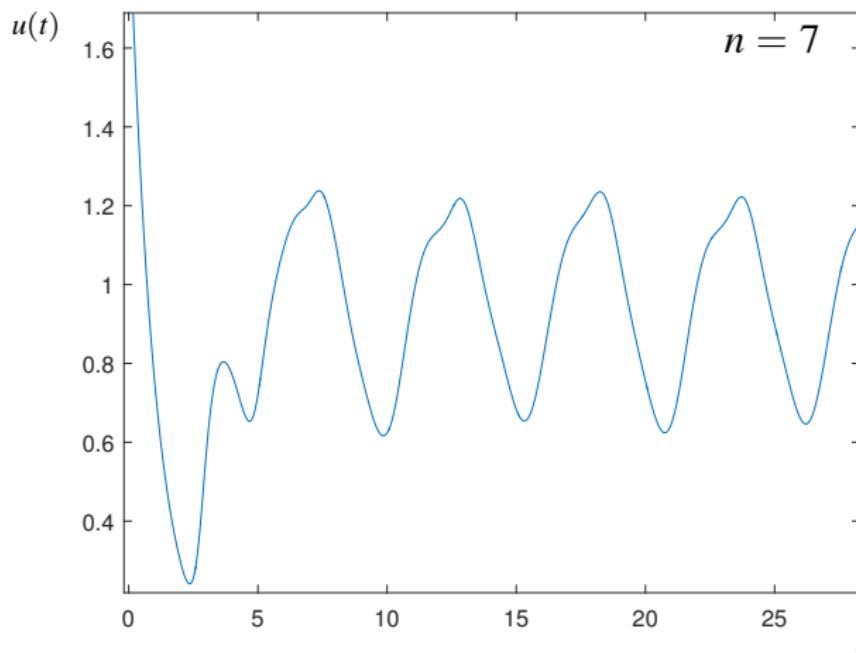
- [Mackey & Glass 1977] (see also scholarpedia article)
- Early toy model of circulating white blood cell numbers
- A scalar equation with chaotic dynamics
- $u(t) \in \mathbb{R}$ , but phase-space  $C = C([-\tau, 0], \mathbb{R})$  is  $\infty$ -dimensional.  
How should we represent solutions??
- Mackey and Glass project into  $\mathbb{R}^2$  by plotting  $u(t-\tau)$  vs  $u(t)$ .
- Equivalently we have  $\mathcal{P} : C \rightarrow \mathbb{R}^2$  defined by

$$\mathcal{P}u_t = (u_t(0), u_t(-\tau))$$



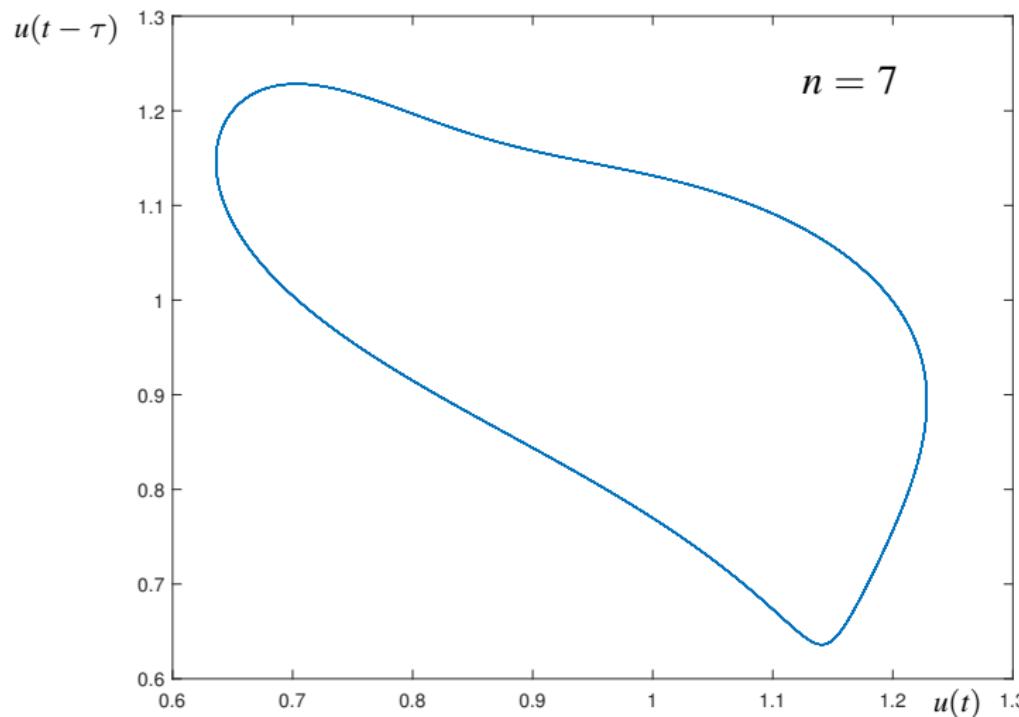
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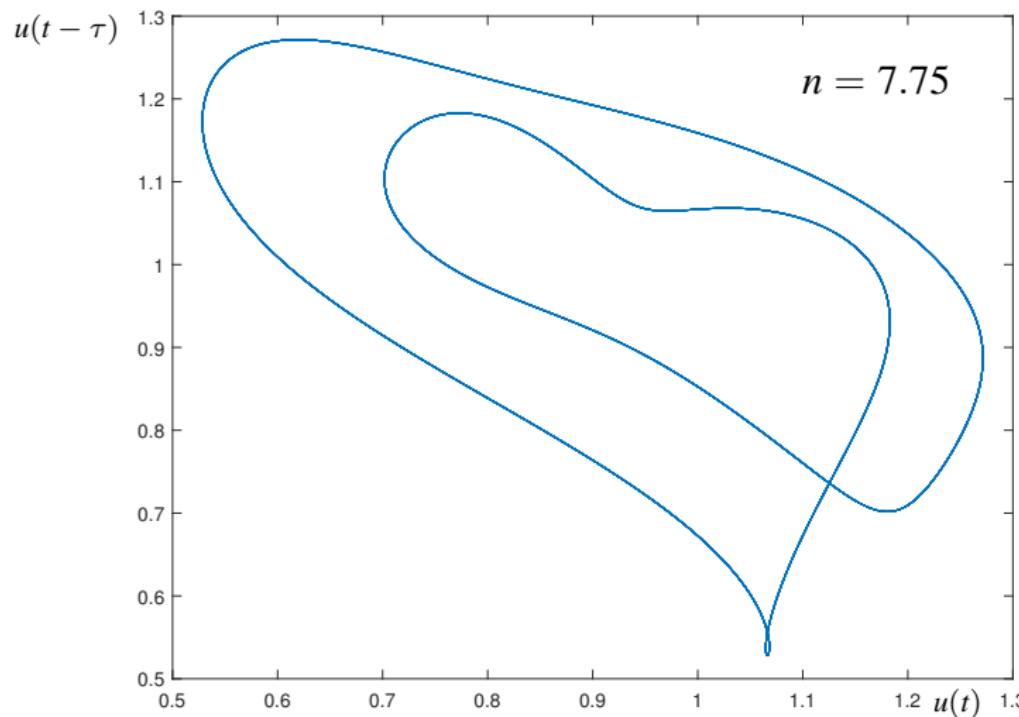
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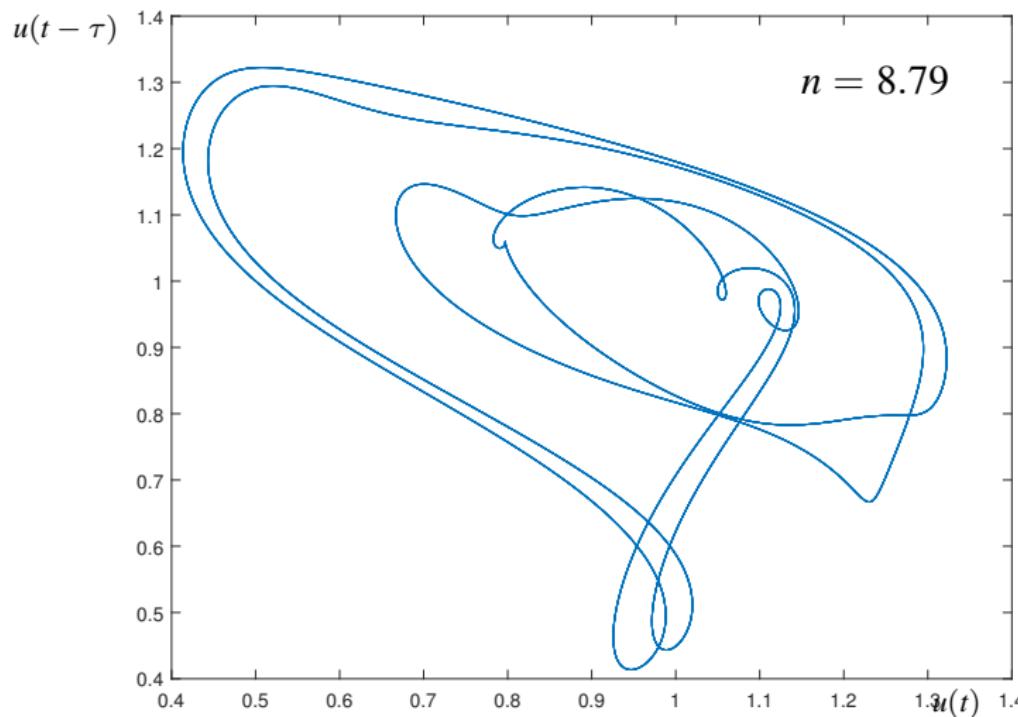
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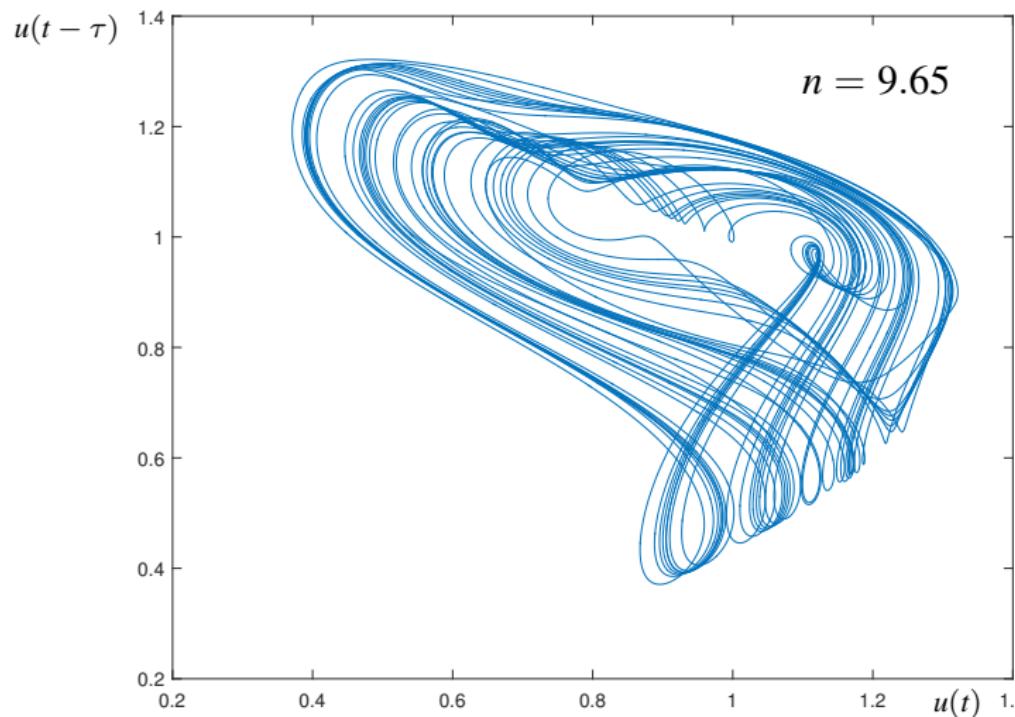
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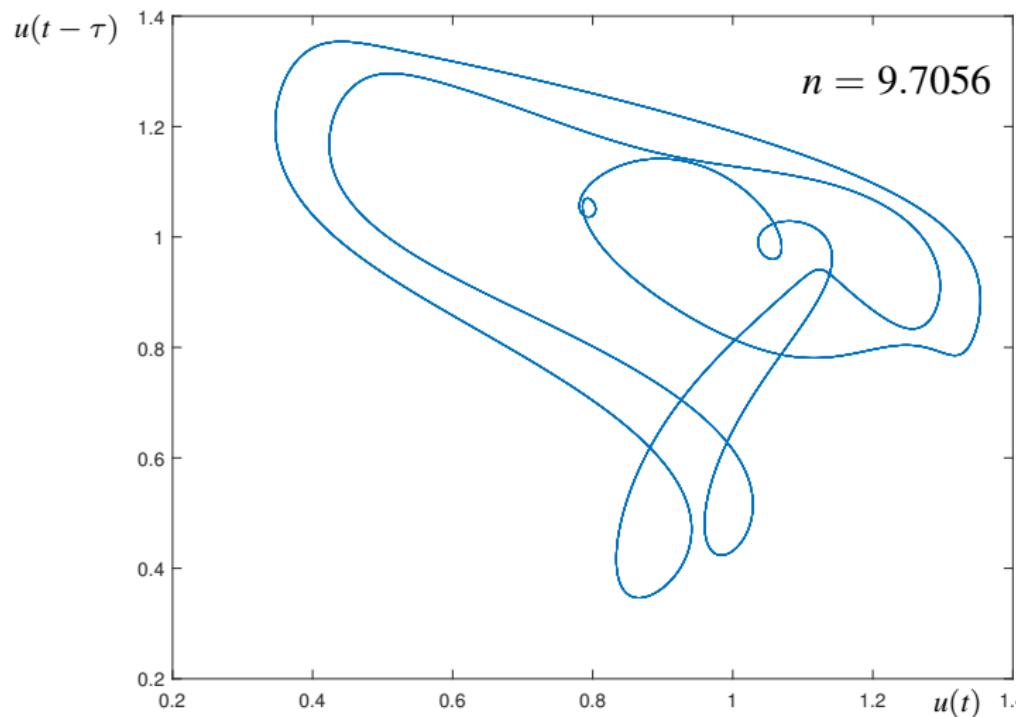
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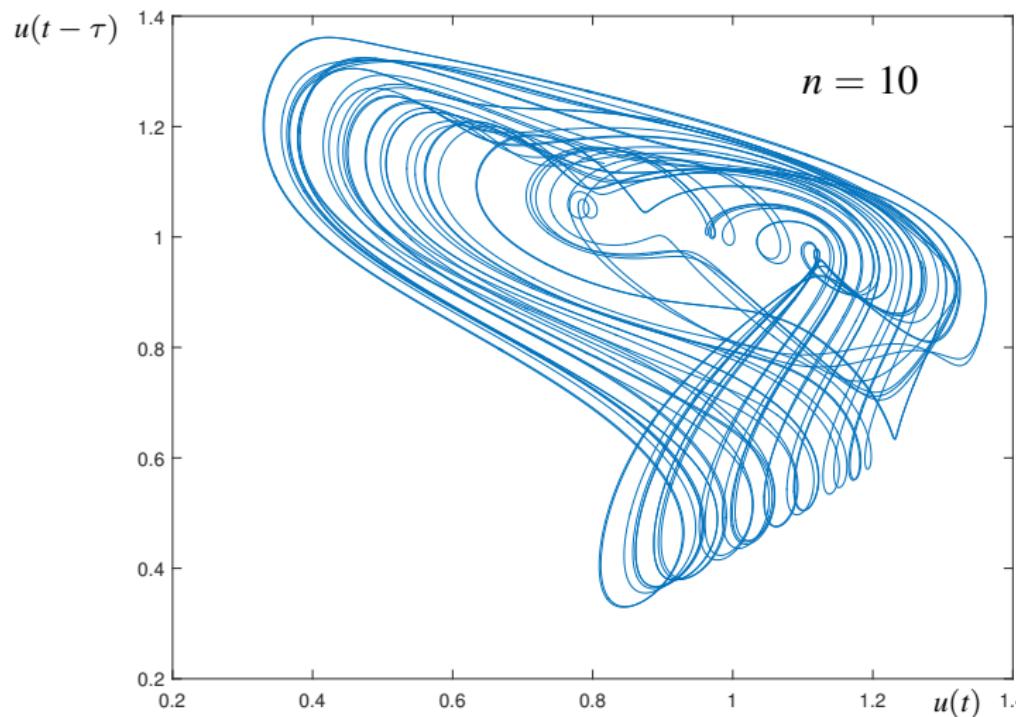
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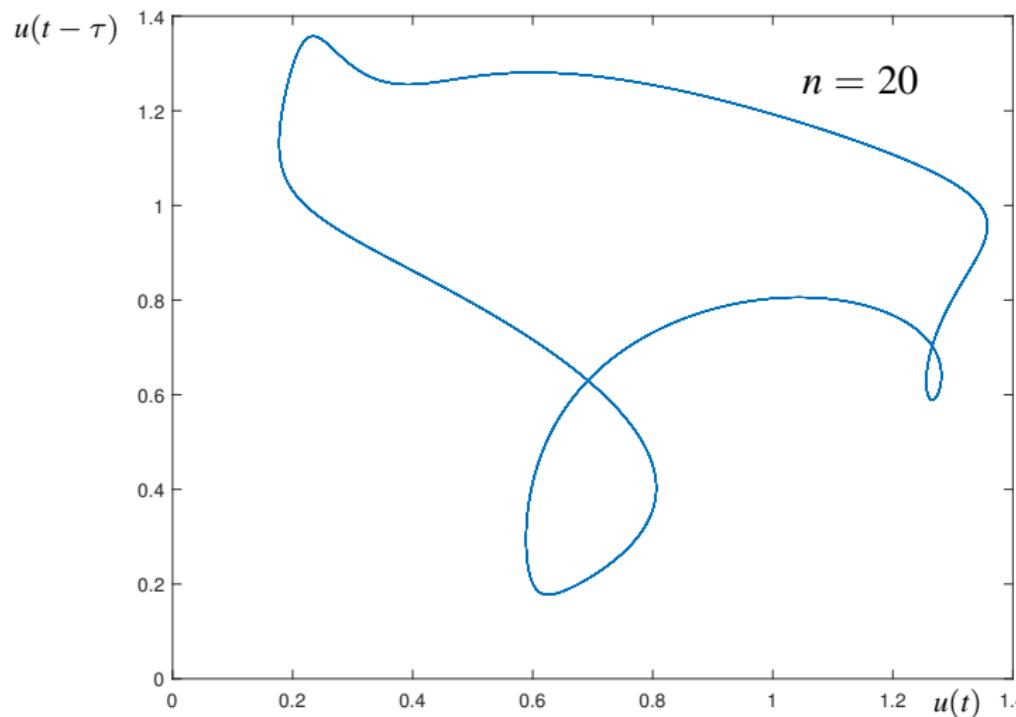
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# Continuation

- Previous Mackey-Glass simulations performed using `dde23`; the matlab fixed delay adaptive step-size dde solver
- It only reveals stable dynamics
- Plots show last 200 time units of a 1000 time unit integration to show asymptotic behaviour
- 20 plot points per time unit (use `deval` to evaluate solution); never use mesh points.
- Reduced tolerances: `AbsTol= 1e - 8; RelTol= 1e - 6.`

## Preaching to the Converted:

We need continuation to study the bifurcations that lead to these dynamics



# Steady states

Consider autonomous DDEs

## Steady States

A steady-state of

$$\dot{u}(t) = f(u(t), u(t - \tau))$$

is a **constant** function  $\varphi \in C = C([-\tau, 0], \mathbb{R}^d)$  st

$$\varphi(\theta) = u^* \quad \forall \theta \in [-\tau, 0], \quad \text{s.t.} \quad f(u^*, u^*) = 0, \quad \forall t \geq t_0$$

- Solving  $f(u^*, u^*) = 0$  is equivalent to setting  $\tau = 0$  and solving for fixed points of resulting ODE; just algebra.
- Stability of steady-state of DDE in  $C$  given by characteristic equation; not directly related to fixed point of ODE in  $\mathbb{R}^d$  unless delay  $\tau$  is small.



# Mackey-Glass Steady-States and Bifurcations

$$\dot{u}(t) = -\gamma u(t) + \beta \frac{u(t-\tau)}{1+u(t-\tau)^n}, \quad u(t) \in \mathbb{R}$$

Setting  $\dot{u}(t) = 0$  and  $u(t) = u(t-\tau) = u$  gives  $\gamma u(1+u^n) = \beta u$  so

Steady-states are  $u = 0$  and  $u = (\beta/\gamma - 1)^{1/n} > 0$  when  $\beta > \gamma > 0$ .  
 In physiology parameters and variables are non-negative.

Linearization at  $u = 0$  is

$$\dot{u}(t) = -\gamma u(t) + \beta u(t-\tau),$$

and  $u = 0$  is stable for  $\beta < \gamma$  ( $\lambda = 0$  is a char value when  $\beta = \gamma$ ).

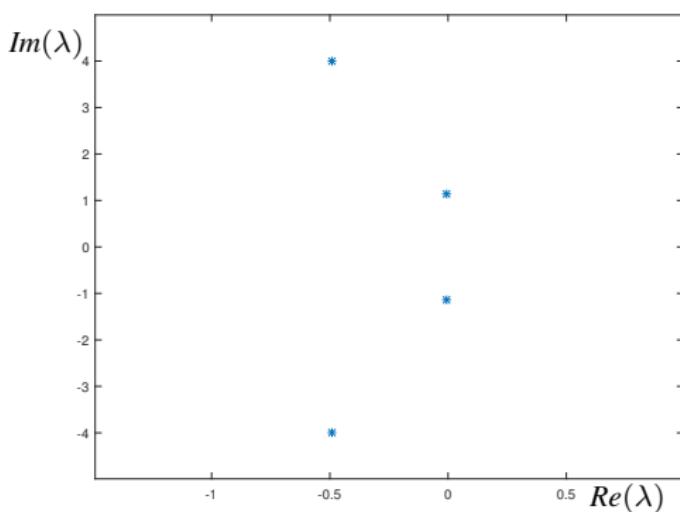
Transcritical bifurcation at  $u = 0, \beta = \gamma$ .



# Mackey-Glass Steady-States and Bifurcations

At non-trivial steady-state characteristic equation is

$$\lambda/\gamma + 1 - (1 - n(1 - \gamma/\beta))e^{-\lambda\tau} = 0$$



- For  $\tau = \beta = 2$ ,  $\gamma = 1$  and varying  $n$
- Close to  $n = 5$  a pair of characteristic values cross imaginary axis left to right
- Steady-state loses stability; a Hopf bifurcation occurs
- Characteristic values computed numerically using DDEBiftool.



# DDEBiftool

## DDEBiftool

A matlab/octave package for bifurcation analysis of DDEs

- Maintained by Jan Sieber
- Downloadable from sourceforge
- Manual also at arXiv:1406.7144
- Learn by following the demos

## Getting Started

- ① Download. Add to matlab path.
- ② Define problem
- ③ Initialize a branch
- ④ Continue it
- ⑤ GetStability & Branch switch

Manual is not always exhaustive



# DDEBiftool Set Up

Mackey-Glass with  $\gamma = 1, \beta = 2$

```
gamma=1.0; beta_ind=1; n_ind=2; tau_ind=3;
f=@(x,xtau,beta,n)beta*xtau./(1+xtau.^n)-gamma*x;
funcs=set_funcs('sys_rhs',@(xx,p)f(xx(1,1,:))...
,xx(1,2,:),p(1),p(2)),...
'sys_tau',@()tau_ind,'x_vectorized',true);
beta0=2; n0=4; tau0=2;
```

Nontrivial Steady-state branch

```
x0=(beta0-1)^(1/n0); contpar=n_ind;
nontriv_eqs=SetupStst(funcs,'x',x0,'parameter',...
[beta0,n0,tau0],'step',0.1,'contpar',contpar,...
'max_step',[contpar,0.1],'max_bound',[contpar,21]);
nontriv_eqs=br_contin(funcs,nontriv_eqs,1000);
nontriv_eqs=br_stabl(funcs,nontriv_eqs,0,1);
unst_eqs=GetStability(nontriv_eqs);
ind_hopf=find(unst_eqs<2,1,'last');
```



# Hopf and Periodic Branches

## Verify Bifurcation

```
evals=nontriv_eqs.point(ind_hopf).stability.10;  
plot(real(evals),imag(evals),'*')
```



# Hopf and Periodic Branches

## 2-Follow Hopf

```
[hbranch,suc]=SetupHopf(funcs,nontriv_eqs,ind_hopf,...  
'contpar',[n_ind,tau_ind],'max_bound',...  
[n_ind,21;tau_ind,4],'dir',n_ind,'step',1e-3);  
hbranch=br_contin(funcs,hbranch,200);  
hbranch=br_rvers(hbranch);  
hbranch=br_contin(funcs,hbranch,200);
```



# Hopf and Periodic Branches

## 2-Follow Hopf

```
[hbranch,suc]=SetupHopf(funcs,nontriv_eqs,ind_hopf,...  
'contpar',[n_ind,tau_ind],'max_bound',...  
[n_ind,21;tau_ind,4],'dir',n_ind,'step',1e-3);  
hbranch=br_contin(funcs,hbranch,200);  
hbranch=br_rvers(hbranch);  
hbranch=br_contin(funcs,hbranch,200);
```

## 1-Compute Periodic Orbit

```
[per_orb,suc]=SetupPsol(funcs,nontriv_eqs,ind_hopf,...  
'print_residual_info',1,'intervals',20,'degree',4,...  
'max_bound',[contpar,21],'max_step',[contpar,0.1]);  
per_orb=br_contin(funcs,per_orb,200);  
per_orb=br_stabl(funcs,per_orb,0,1);  
[nunst_per,dom]=GetStability(per_orb,...  
'exclude_trivial',true);  
ind_pd=find(diff(nunst_per)==1);
```



# Period Doubling

## 2-Follow Branch of Period Doublings

```
[pdfuncs,pdbranch1,suc]=SetupPeriodDoubling(funcs,...  
per_orb,ind_pd(1),'contpar',[n_ind,tau_ind],...  
'max_bound',[n_ind,21;tau_ind,4],'dir',n_ind,...  
'step',1e-3);  
pdbranch1=br_contin(pdfuncs,pdbranch1,200);  
pdbranch=br_rvers(pdbranch1);  
pdbranch=br_contin(pdfuncs,pdbranch,200);
```

## 1-Continue Period-Doubled Solution

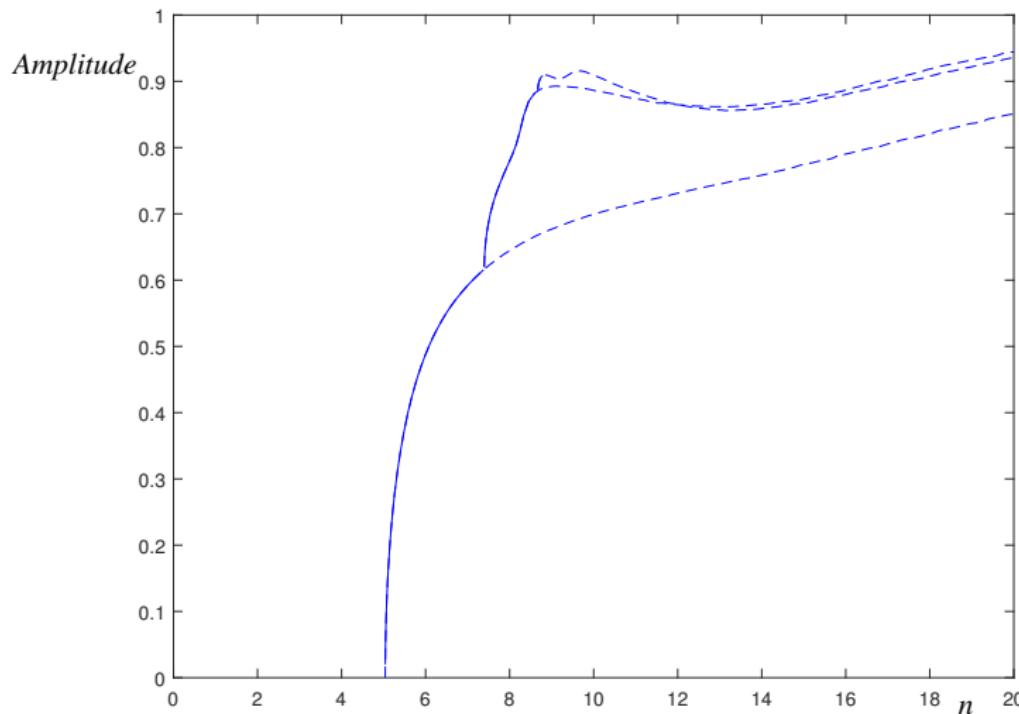
```
[per2,suc]=DoublePsol(funcs,per_orb,ind_pd(1));  
per2=br_contin(funcs,per2,200);  
per2=br_stabl(funcs,per2,0,1);  
[nunst_per2,dom,triv_defect]=GetStability(per2,...  
'exclude_trivial',true)
```

And onwards to more period doublings



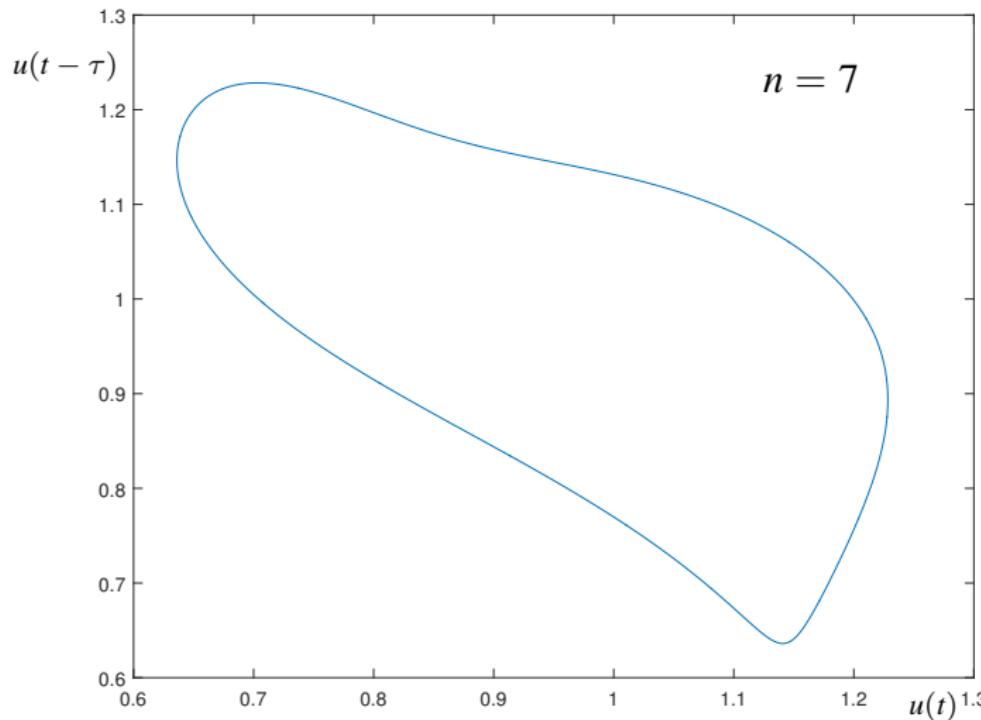
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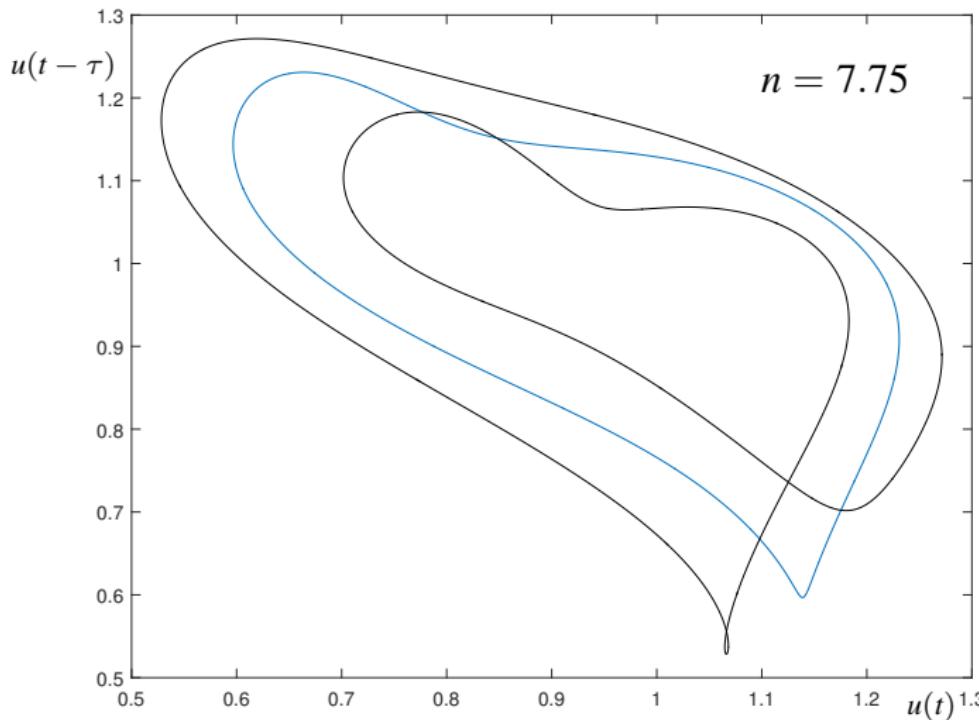
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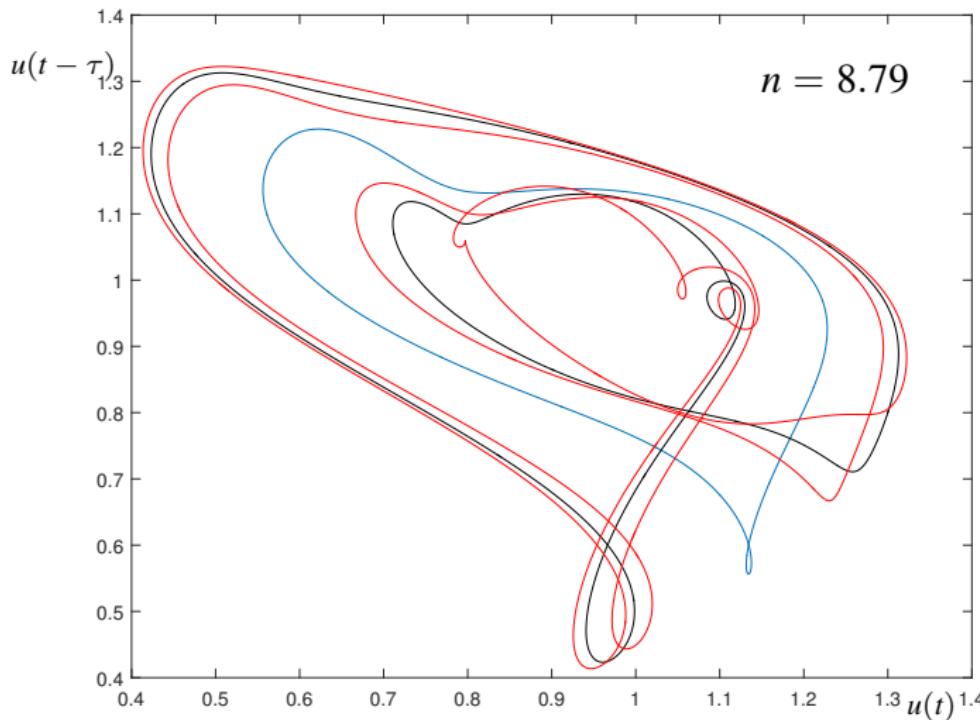
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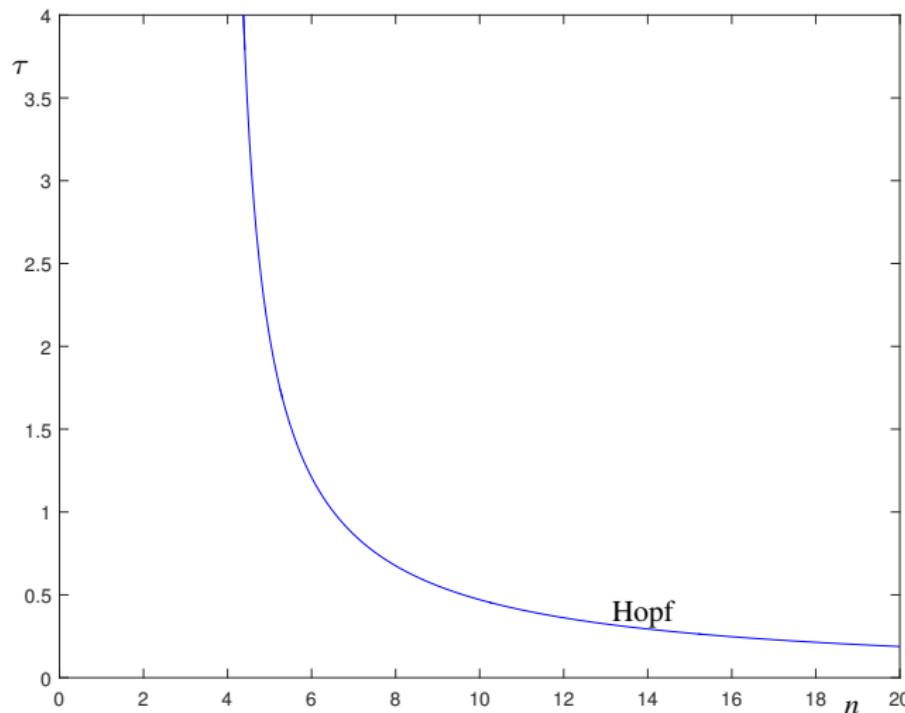
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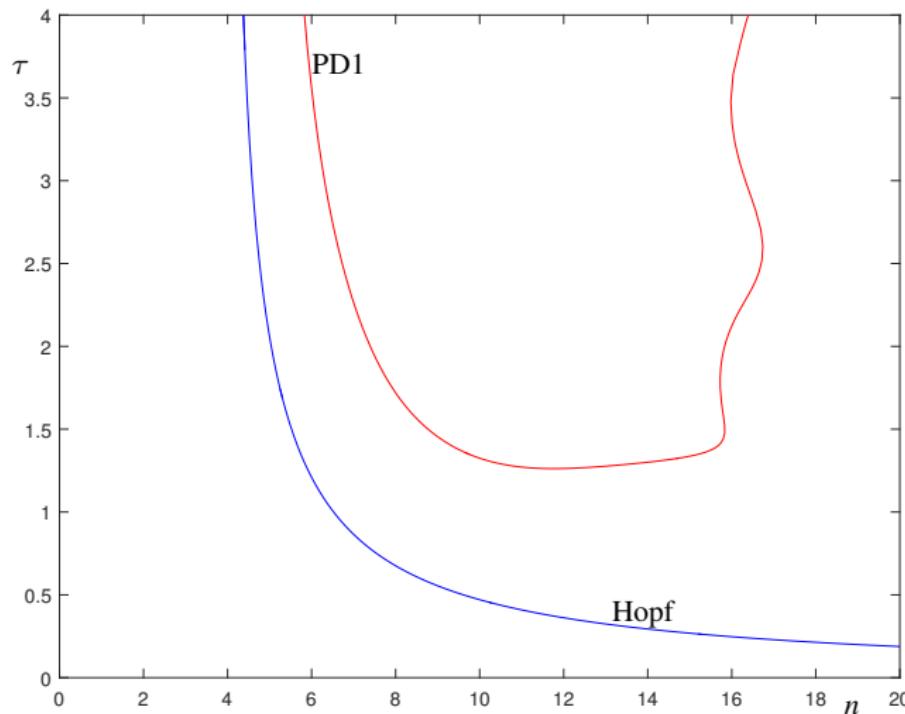
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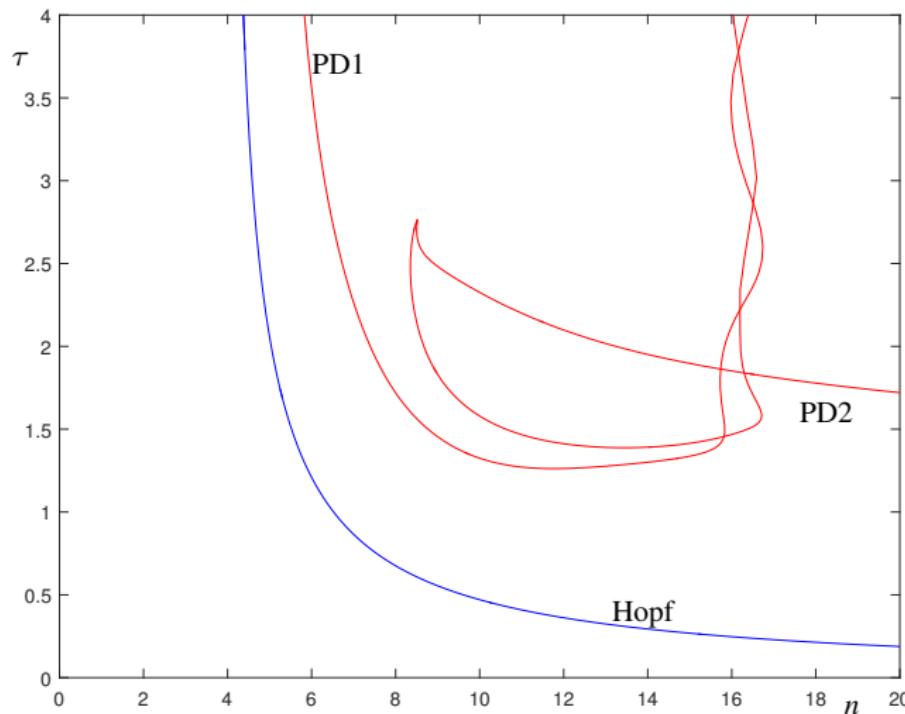
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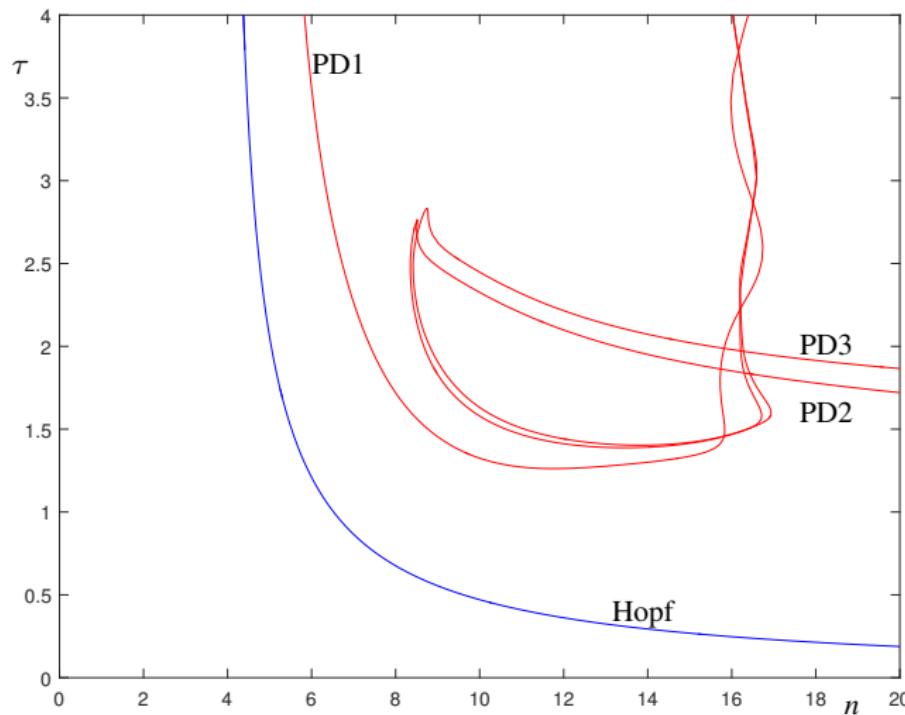
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