

$$\textcircled{1} \text{ (a) } \frac{dy}{dt} = y^2 \cos t$$

$$\int \frac{dy}{y^2} = \int \cos t \, dt$$

$$-\frac{1}{y} = \sin t + c$$

$$y = \frac{-1}{\sin t + c}$$

( $y=0$  is a missing soln, but it does not satisfy initial condition).

$$1 = y(\pi/2) = \frac{-1}{1+c}$$

$$\therefore 1+c = -1 \quad \text{ie } c = -2$$

$$y(t) = \frac{1}{2 - \sin t}$$

$$\text{(b) } \frac{dy}{dt} - 5y = e^t$$

$$\text{linear. } \mu(t) = \exp\left(\int -5 dt\right) = e^{-5t}$$

$$e^{-5t} \frac{dy}{dt} - 5e^{-5t} y = e^{-4t}$$

$$\frac{d}{dt} (e^{-5t} y) = e^{-4t}$$

$$e^{-5t} y = -\frac{1}{4} e^{-4t} + c$$

$$y = -\frac{1}{4} e^t + c e^{5t}$$

②

$$\frac{dy}{dt} = y^2 - t \quad y(2) = 1$$

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$$f(t, y) = y^2 - t \quad t_0 = 2, y_0 = 1$$

(a) There is a unique solution.

$f$  is continuous for all  $t, y$  + so at  $(2, 1)$   
 $\frac{\partial f}{\partial y} = 2y$  which is also continuous + so at  $(2, 1)$ .

$$(b) h = \frac{2.4 - 2}{2} = 0.2$$

$$t_0 = 2, y_0 = 1, f(t, y) = y^2 - t$$

Step 1  $m_1 = f(t_0, y_0) = -1$

$$m_2 = f(t_0 + h, y_0 + h m_1) = f(2.2, 0.8) = -1.56$$

$$\begin{aligned} y_1 &= y_0 + \frac{h}{2} (m_1 + m_2) \\ &= 1 + \frac{0.2}{2} (-1 - 1.56) \\ &= 0.744 \end{aligned}$$

Step 2  $m_1 = f(t_1, y_1) = -1.6465$

$$\begin{aligned} m_2 &= f(t_1 + h, y_1 + h m_1) \\ &= f(2.4, 0.4147) \\ &= -2.228 \end{aligned}$$

$$y_2 = y_1 + \frac{h}{2} (m_1 + m_2) = 0.3565$$

(c) With 10 steps instead of 2,  $h$  would become  $\frac{h}{5}$

Since Improved Euler has order 2

$$E\left(\frac{h}{5}\right) \approx C\left(\frac{h}{5}\right)^2 = \frac{Ch^2}{25} = \frac{E(h)}{25}$$

Expect the error to be 25 times less.

$$(3)(a) \quad \frac{dP}{dt} = 0.05P\left(1 - \frac{P}{80}\right) - 0.5$$

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(b) First find the equilibrium solutions.

$$\frac{dP}{dt} = 0 \Leftrightarrow 0.05P\left(1 - \frac{P}{80}\right) - 0.5 = 0$$

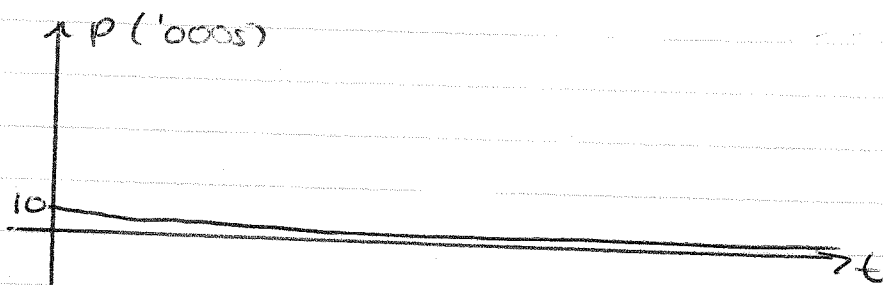
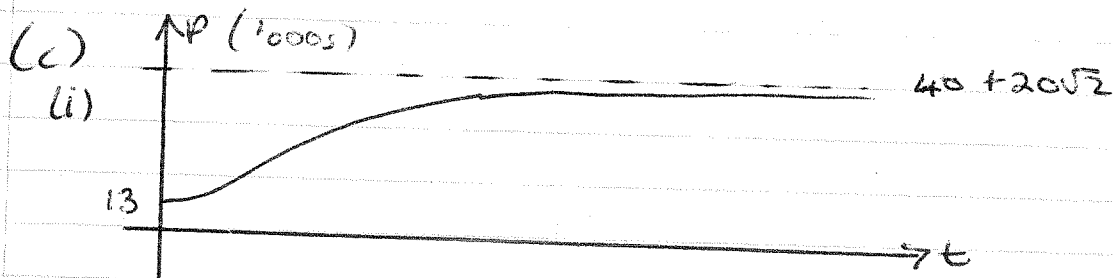
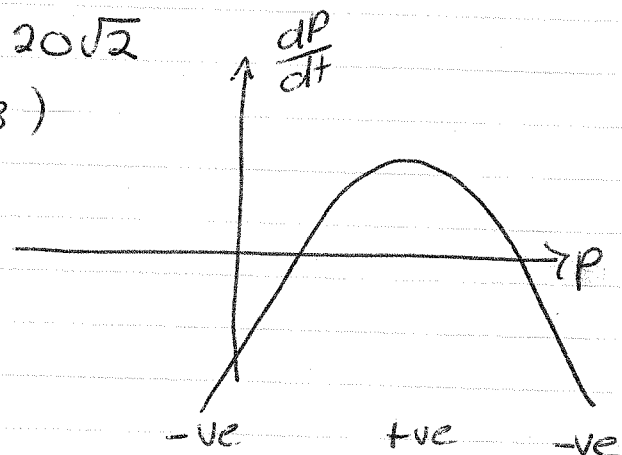
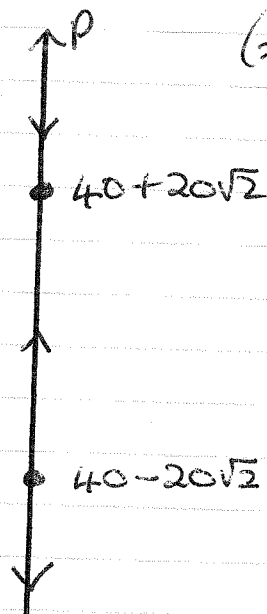
$$\Leftrightarrow 0.05P(80 - P) - 0.5 \times 80 = 0$$

$$\Leftrightarrow -0.05P^2 + 4P - 40 = 0$$

$$\Leftrightarrow P = \frac{-4 \pm \sqrt{16 - 8}}{-0.1}$$

$$= 40 \pm 20\sqrt{2}$$

( $\approx 11.7$  &  $68.3$ )



④  $\frac{dy}{dt} = (y-1)(y-\alpha)$

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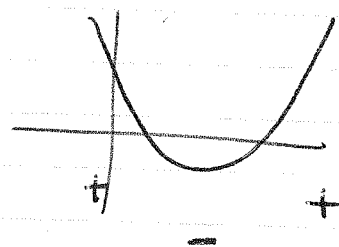
(a)  $\frac{dy}{dt} = (y-1)(y-2)$   
 $= 0$  when  $y=1, y=2$



$f(y) = y^2 - 3y + 1$

$\frac{\partial f}{\partial y} = 2y - 3$

OR



$\left. \frac{\partial f}{\partial y} \right|_1 = -1 \quad \therefore \text{sink}$

$\left. \frac{\partial f}{\partial y} \right|_2 = 1 \quad \therefore \text{source}$

OR Draw phase line from above quadratic + see that 1 is sink + 2 is source.

(b) Equilibrium when  $y=1$  or  $y=\alpha$ .

$f(y) = y^2 - (\alpha+1)y + \alpha, \quad \frac{\partial f}{\partial y} = 2y - (\alpha+1)$

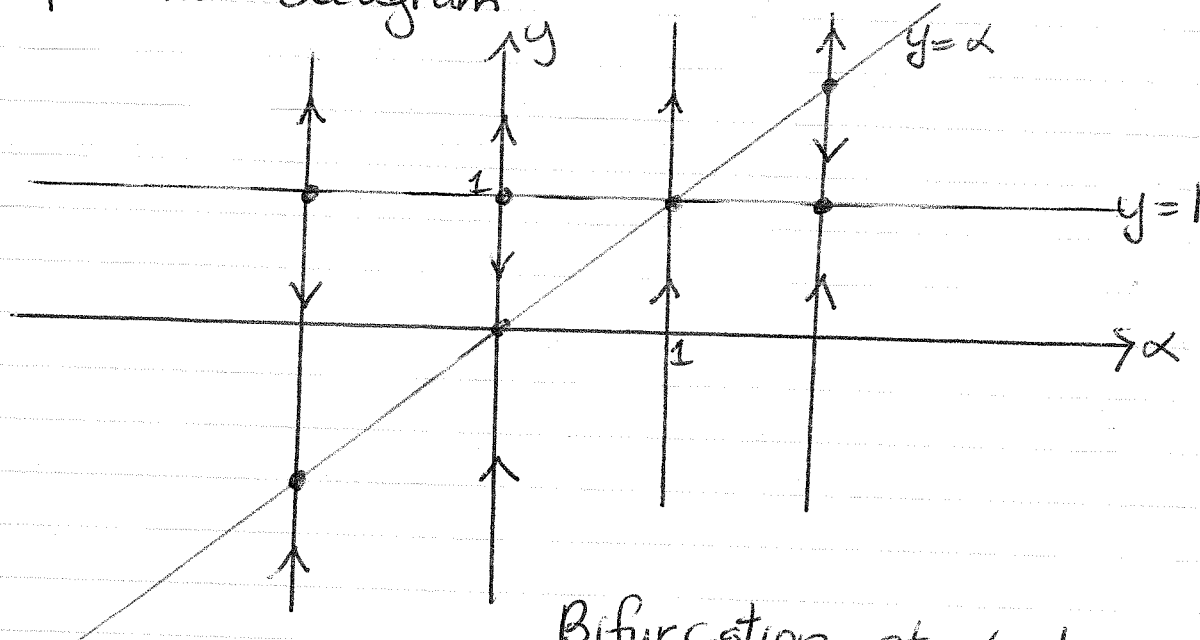
2 equilibria if  $\alpha \neq 1$ , otherwise 1.

$\left. \frac{\partial f}{\partial y} \right|_1 = 1 - \alpha \quad \begin{array}{l} \text{source } \alpha < 1 \\ \text{sink } \alpha > 1 \end{array}$

$\left. \frac{\partial f}{\partial y} \right|_\alpha = \alpha - 1 \quad \begin{array}{l} \text{sink } \alpha < 1 \\ \text{source } \alpha > 1 \end{array}$

If  $\alpha=1$ ,  $\partial f(y) = (y-1)^2$  which is always positive when  $y \neq 1$   $\therefore$  node.

Bifurcation diagram



Bifurcation at  $\alpha = 1$ .

⑤ At equilibrium

$$\left. \begin{aligned} x + z &= 0 \\ x^3 + y &= 0 \\ y - z &= 0 \end{aligned} \right\}$$

i.e.

$$x = -z$$

$$y = z$$

$$\begin{aligned} 0 = x^3 + y &= -z^3 + z = z(1 - z^2) \\ &= z(1 - z)(1 + z) \end{aligned}$$

$$z = 0 \text{ or } 1 \text{ or } -1$$

When  $z = 0$ ,  $x = y = 0$

When  $z = 1$ ,  $x = -1$ ,  $y = 1$

When  $z = -1$ ,  $x = 1$ ,  $y = -1$

Equilibrium solutions are

$$(0, 0, 0)$$

$$(-1, 1, 1)$$

$$(1, -1, -1)$$

⑥

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$$\frac{dx}{dt} = y^2 = f(t, x, y)$$

$$\frac{dy}{dt} = t - x = g(t, x, y)$$

(a)  $f$  &  $g$  are both continuous at  $(0, 1, 2)$

$$\frac{\partial f}{\partial x} = 0 \quad \frac{\partial f}{\partial y} = 2y, \quad \frac{\partial g}{\partial x} = -1, \quad \frac{\partial g}{\partial y} = 0$$

These are all continuous at  $(0, 1, 2)$

∴ there is a unique solution.

$$(b) h = \frac{0.1 - 0}{1} = 0.1$$

$$\begin{aligned} x(0.1) &\approx x(0) + h f(t_0, x_0, y_0) \\ &= 1 + 0.1 \times 4 \\ &= 1.4 \end{aligned}$$

$$\begin{aligned} y(0.1) &\approx y(0) + h g(t_0, x_0, y_0) \\ &= 2 + 0.1(0 - 1) \\ &= 1.9 \end{aligned}$$