# Maths 260 Assignment 2 Sample Solutions

April 19, 2007

Due:

#### Total Marks for Assignment 2: 40

**1.** Note that

$$f(t,y) = 1 - t + 4y.$$

(a) There are two steps to do so h = 0.1. Also  $t_0 = 0$  and  $y_0 = 1$ . Step 1

$$m_1 = f(t_0, y_0) = 5$$
  

$$m_2 = f(t_0 + h, y_0 + hm_1)$$
  

$$= f(-0.1, 1.5) = 6.9$$
  

$$y_1 = y_0 + \frac{h}{2}(m_1 + m_2)$$
  

$$= 1 + \frac{0.1}{2}(5 + 6.9) = 1.595$$
  

$$t_1 = 0.1$$

Step 2

$$m_1 = f(0.1, 1.595) = 7.28$$
  

$$m_2 = f(0.2, 2.323) = 10.092$$
  

$$y_2 = 1.595 + \frac{.1}{2}(7.28 + 10.092)$$
  

$$= 2.4636$$
  

$$t_2 = 0.2$$

Therefore  $y(0.2) \approx 2.4636$ .

(b) There is one step to do so h = 0.2. Also  $t_0 = 0$  and  $y_0 = 1$  Step 1

$$m_{1} = f(t_{0}, y_{0}) = 5$$

$$m_{2} = f(t_{0} + \frac{h}{2}, y_{0} + \frac{h}{2}m_{1})$$

$$= f(0.1, 1.5) = 6.9$$

$$m_{3} = f(t_{0} + \frac{h}{2}, y_{0} + \frac{h}{2}m_{2})$$

$$= f(0.1, 1.69) = 7.66$$

$$m_{4} = f(t_{0} + h, y_{0} + hm_{3})$$

$$= f(0.2, 2.532) = 10.928$$

$$y_{1} = y_{0} + \frac{h}{6}(m_{1} + 2m_{2} + 2m_{3} + m_{4})$$

$$= 1 + \frac{0.2}{6}(5 + 2 \times 6.9 + 2 \times 7.66 + 10.928)$$

$$= 2.5016$$

Therefore  $y(0.2) \approx 2.5016$ .

## Total marks for Q1: 6

2. This is a linear differential equation so write it as

$$\frac{dy}{dt} - 4y = 1 - t.$$

The integrating factor is  $\mu(t) = exp(\int (-4)dt) = e^{-4t}$ .

$$e^{-4t}\frac{dy}{dt} - 4e^{-4t}y = e^{-4t}(1-t)$$

$$\frac{d}{dt}(ye^{-4t}) = e^{-4t}(1-t)$$

$$ye^{-4t} = \int e^{-4t}(1-t)dt$$

$$= -\frac{3}{16}e^{-4t} + \frac{1}{4}te^{-4t} + c$$

$$y = -\frac{3}{16} + \frac{1}{4}t + ce^{4t}$$

$$1 = y(0)$$

$$= -\frac{3}{16} + c$$

$$c = \frac{19}{16}$$

$$y(t) = -\frac{3}{16} + \frac{1}{4}t + \frac{19}{16}e^{4t}$$

$$y(0.2) = 2.5053$$

Therefore the error in 1(a) is  $4.2 \times 10^{-2}$  and in 1(b) it is  $3.7 \times 10^{-3}$ . The error for the Runge-Kutta method is smaller even though the stepsize was twice as large. Each method required 4 function evaluations so the Runge-Kutta is more efficient. Total marks for Q2: 7

**3.** (a) The formula for effective order at stepsize h is

$$q = \frac{\ln |E(2h)| - \ln |E(h)|}{\ln 2}.$$

i. At h = 0.125,

$$q = \frac{\ln|E(0.25)| - \ln|E(0.125)|}{\ln 2} = \frac{\ln 1.45 \times 10^{-3} - \ln 2 \times 10^{-4}}{\ln 2} = 2.858$$

ii. At 
$$h = 0.03125$$
  
$$q = \frac{\ln |E(0.0625)| - \ln |E(0.03125)|}{\ln 2} = \frac{\ln 2.63 \times 10^{-5} - \ln 3.37 \times 10^{-6}}{\ln 2} = 2.9642$$

(b) The order is probably 3 because as  $h \to 0$ , q appears to be approaching 3. Total marks for Q3: 3

## **4.** (a) The direction field is



- (b)  $f(t,y) = 3(t+y)^{1/2}$  which is defined only if  $t+y \ge 0$ . The existence theorem says that a solution through  $(t_0, y_0)$  will exist if f is continuous (and defined) at  $(t_0, y_0)$ , so a solution exists if  $t_0 + y_0 > 0$ . We can see on the direction field that for y < -t that the slope marks do not exist (they look a bit like zero slope but they do not exist).
- (c)  $\frac{\partial f}{\partial y} = 3/(2(t+y)^{1/2})$ , which exists and is continuous at all  $(t_0, y_0)$  where  $t_0 + y_0 > 0$ . Again this is what we see on the direction field.

### Total marks for Q4: 7

5. (a) The equilibrium solutions are when  $y^2 - y^3 = 0$  ie  $y^2(1 - y) = 0$  ie at y = 0 and y = 1. The phase line is



- (b) y = 0 is a node and y = 1 is a sink.
- (c) The solutions are shown below on a direction field, but the students should just sketch them by hand.



#### Total marks for Q5: 6

6. (a) The differential equation to model the population is

$$\frac{dP}{dt} = 0.1P(1 - \frac{P}{100}) - \alpha.$$

(b) The equilibrium solutions are  $50 \pm 10\sqrt{10}$ . The phase line will be This means that the

minimum number required is  $50 - 10\sqrt{10}$  which means about 18,400 fish.

(c) The curve for the bifurcation diagram will be

$$\alpha = 0.1P(1 - \frac{P}{100})$$

which will be a parabola on its side centred about P = 50.



Total marks for Q6: 7

7. This is a linear differential equation and the integrating factor will be  $e^{at}$ . Multiply through by this. For  $a \neq \lambda$ ,

$$e^{at}\frac{dy}{dt} + ae^{at}y = be^{at}e^{-\lambda t}$$
$$\frac{d}{dt}(e^{at}y) = be^{(a-\lambda)t}$$
$$e^{at}y = \frac{b}{a-\lambda}e^{(a-\lambda)t} + c$$
$$y = \frac{b}{a-\lambda}e^{-\lambda t} + ce^{-at}$$

Since  $\lambda$  and a are positive,  $y \to 0$  as  $t \to \infty$ . When  $a = \lambda$ , then we get

$$\frac{d}{dt}(e^{at}y) = b$$
$$e^{at}y = bt + c$$
$$y = (bt + c)e^{-at}$$

Some plots are shown below. It appears that  $y \to 0$  as  $t \to \infty$  just as when  $a \neq \lambda$ . Total marks for Q7: 4